

Edit Distance of Finite-Valued Transducers

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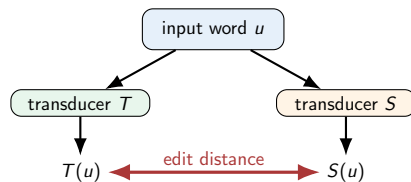
Comparing transformations

Transducers model input-output behaviour

A finite-state transducer reads an input word and produces output word(s):

$$\mathcal{T} \subseteq A^* \times B^*.$$

- ▶ Equality asks: are two transformations identical?
- ▶ Distance asks: how far apart are they?
- ▶ Edit distance is natural for text-producing systems.



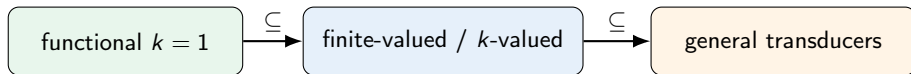
Finite-valued transducers

Definition

A transducer is ***k*-valued** if every input has at most k outputs:

$$\forall u \in A^*, \quad |\mathcal{T}(u)| \leq k.$$

It is ***finite-valued*** if it is k -valued for some fixed $k \in \mathbb{N}$.



Why this class?

Many problems that are undecidable in general for transducers become decidable under finite-valuedness.

Problem landscape

Class of transducers	Equivalence / inclusion	Edit distance
Functional	decidable [Gurari et. al. 1983]	computable [Aiswarya et. al. 2024]
Finite-valued	decidable [Culík II et al. 1986]	?
General transducers	undecidable [Fischer et al. 1968]	uncomputable [Aiswarya et. al. 2024]

Question

Is there a more expressive and well-behaved class beyond functional transducers where edit distance remains computable?

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Question

Is there a more expressive and well-behaved class beyond functional transducers where edit distance remains computable?

Yes - finite-valued transducers.

Distance between transducers

For a word metric d and relations $R, S \subseteq A^* \times B^*$:

$$d(R, S) = \begin{cases} \sup_{u \in \text{dom}(R)} H_d(R(u), S(u)), & \text{dom}(R) = \text{dom}(S), \\ \infty, & \text{otherwise.} \end{cases}$$

Here, H_d is the Hausdorff distance, that lifts distance between words to sets of words.

Intuition

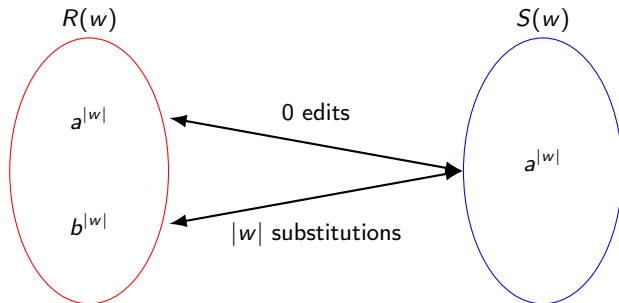
The distance between R and S is the minimal integer K such that, for every input u ,

- ▶ every output of $R(u)$ is within K edits¹ of some output of $S(u)$, and
- ▶ every output of $S(u)$ is within K edits of some output of $R(u)$.

¹edit operations include insertion, deletion, letter-to-letter substitution, ...

Distance Between Relations

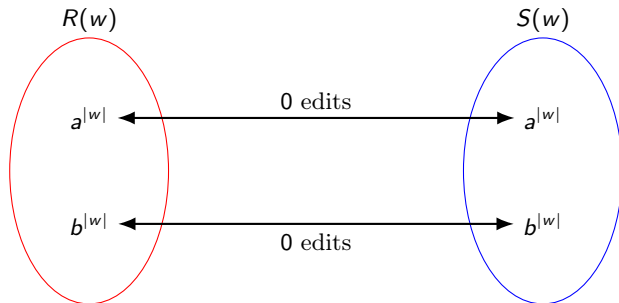
Let $R(w) = \{a^{|w|}, b^{|w|}\}$ and $S(w) = \{a^{|w|}\}$.



$$d(R, S) = \infty.$$

Distance Between Relations

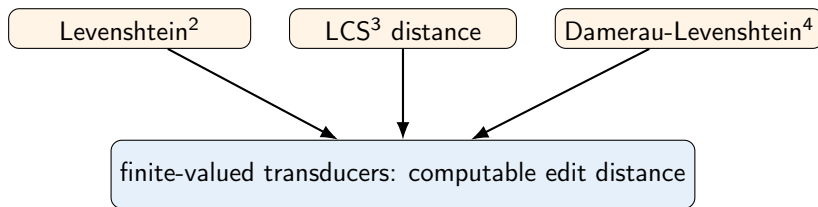
Let $R(w) = \{a^{|w|}, b^{|w|}\}$ and $S(w) = \{a^{|w|}, b^{|w|}\}$.



$$d(R, S) = 0.$$

Theorem

Let T and S be finite-valued transducers. For every distance in the Levenshtein family, $d(T, S)$ is computable.

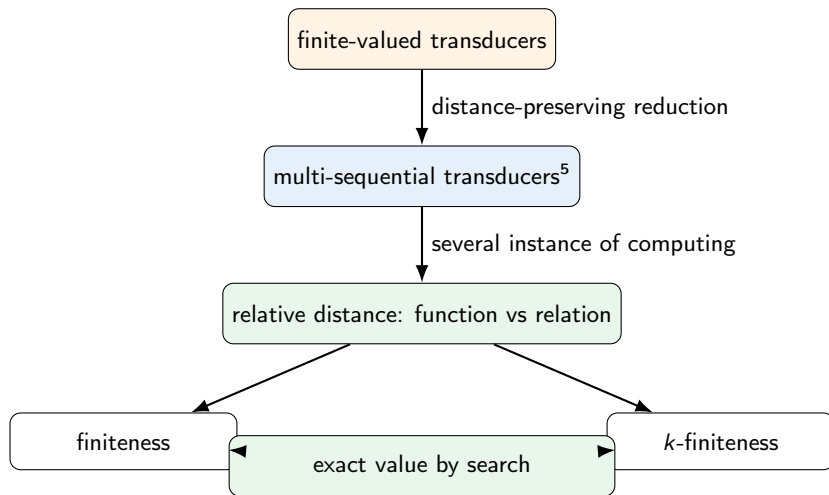


²Levenshtein — insertion, deletion and substitution

³LCS — insertion and deletion

⁴Damerau Levenshtein — insertion, deletion, substitution and swapping adjacent letters

High-level proof strategy



⁵finite union of sequential transducers (those that are deterministic in the input)

Step 1: finite-valued to multi-sequential

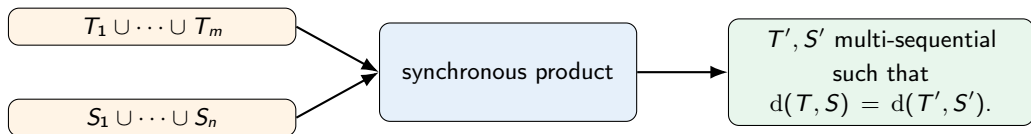
Every finite-valued transducer can be decomposed into a finite union of functional transducers:

$$T \equiv T_1 \cup \dots \cup T_m, \quad S \equiv S_1 \cup \dots \cup S_n, \quad \text{dom}(T) = \text{dom}(S)$$

The construction builds the multi-sequential transducers T' and S' with a common underlying product automaton $\mathcal{A}$ such that

- ▶ $\mathcal{A}$ synchronizes runs of all components of T and S .
- ▶ Its input alphabet are tuples of component transitions, making $\mathcal{A}$ deterministic.
- ▶ Its states records the state reached by the current run and the set of reachable states in each of the components.
- ▶ Its accepting states ensure that all accepting component runs are represented by a global run of $\mathcal{A}$.

$$\{(T(w), S(w)) \mid w \in \text{dom}(T)\} = \{(T'(w), S'(w)) \mid w \in \text{dom}(T')\}$$



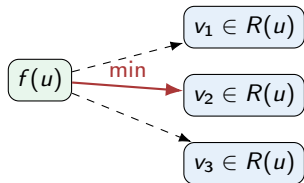
Step 2: multi-sequential distance via relative distance

Definition (Relative distance)

For a function f and a relation R ,

$$\vec{d}(f, R) = \begin{cases} \sup_{u \in \text{dom}(f)} \inf_{v \in R(u)} d(f(u), v), & \text{dom}(f) \subseteq \text{dom}(R), \\ \infty, & \text{otherwise.} \end{cases}$$

- ▶ Standard distance between a function and a relation is too strong.
- ▶ It requires comparing the function output to *all* outputs of the relation.
- ▶ Relative distance asks for the closest output of the relation.



choose the closest output on each input

Step 2: multi-sequential distance via relative distance

Let $R = f_1 \cup \dots \cup f_m$, $S = g_1 \cup \dots \cup g_n$, where each f_i, g_j is sequential.

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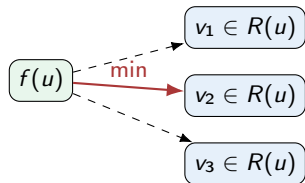
Reduction

If $\text{dom}(R) = \text{dom}(S)$, then

$$d(R, S) = \max\left(\{\vec{d}(f_i, S) : i \in [m]\} \cup \{\vec{d}(g_j, R) : j \in [n]\}\right).$$

Why relative distance is the right notion

- ▶ Standard distance between a function and a relation is too strong.
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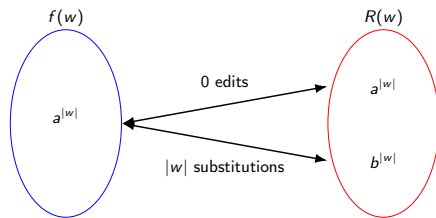
Example

Let $R = f \cup g$, where

$$f(w) = a^{|w|}, \quad g(w) = b^{|w|}.$$

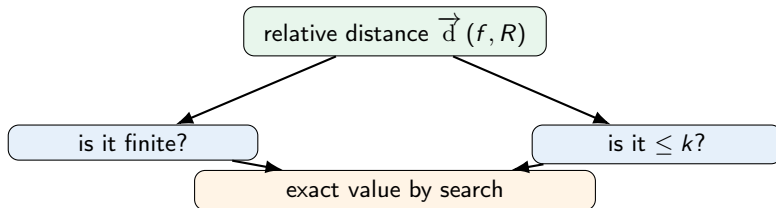
Then $d(R, R) = 0$, but $d(f, R) = \infty$ under the usual edit distance. Relative distance fixes this:

$$\vec{d}(f, R) = 0.$$



Step 3: Computing relative distance

The exact value of $\vec{d}(f, R)$ is computed by reducing to two decision problems.



Key point

For a sequential function f and a multi-sequential relation R , both decision problems are decidable for the Levenshtein family of distances.

The finiteness test uses the known connection between bounded edit distance between sequential transducers and **conjugacy** of loop outputs.

Definition

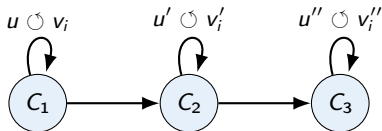
Words u and v are conjugate if $u = xy$ and $v = yx$ for some words x, y .

Theorem (Aiswarya et al. 2024)

Let T and S be functional transducers. For every distance in the Levenshtein family, $d(T, S) < \infty$ iff $\text{dom}(T) = \text{dom}(S)$ and every pair of output words generated by loops in the (trim) Cartesian product of T and S is conjugate.

Finiteness: structural characterisation

Let f be a sequential function and $R = g_1 \cup \dots \cup g_n$, where each g_i is sequential.

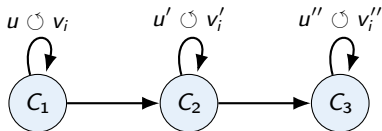


one common index i witnesses boundedness along the path

For the product of f with the components of R

Finiteness: structural characterisation

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one common index i witnesses boundedness along the path

For the product of f with the components of R :

- ▶ decompose the product into directed acyclic graph of SCC paths.
- ▶ along each path, find one component of R that stays boundedly close to f .
- ▶ boundedness follows from conjugacy of corresponding loop outputs.

k -finiteness: finite-state search over edit budgets

To check whether $\vec{d}(f, R) \leq k$, build an NFA $A_{C,k}$.

Idea

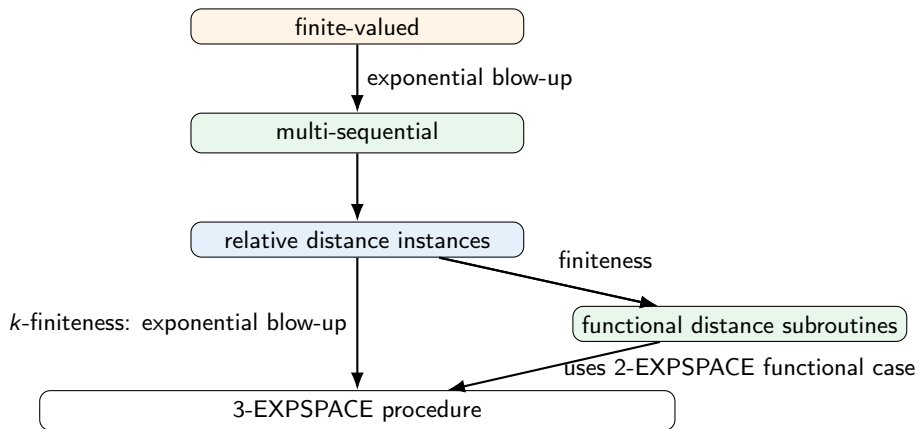
$A_{C,k}$ reads an input word and simulates the product of f with the components of R . It stores:

- ▶ a remaining edit budget for each component;
- ▶ the unmatched leftover between the output of f and that component;
- ▶ a word is accepted if it reaches a state where at least one component has a non-negative remaining budget.

Then:

$$\vec{d}(f, R) \leq k \iff L(A_{C,k}) = \text{dom}(f).$$

So the problem reduces to language equivalence for finite automata.



Lower bound

Computing edit distance is at least PSPACE-hard, since equivalence reduces to checking whether the distance is zero.

Main contribution

We show that the edit distance of finite-valued transducers is computable for the Levenshtein family of distances.

Future work

- ▶ Optimise the efficiency of the construction.
- ▶ Extend the approach to other distances: Hamming distance, transpositions, and beyond.
- ▶ Study edit distance of broader classes of rational and regular relations.

Thank you!